

# CSE 150A-250A AI: Probabilistic Methods

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## Lecture 3

Fall 2025

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Slides adapted from previous versions of the course (Prof. Lawrence, Prof. Alvarado, Prof Berg-Kirkpatrick)

# Agenda

Review

Joint Distributions and Inference

Alarm Example

Belief networks

# Review

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- Types of probabilities:

$P(X, Y)$  joint

$P(Y|X)$  conditional

$P(X)$  unconditional (or marginal)

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- Useful rules:

$P(A, B, C, \dots) = P(A)P(B|A)P(C|A, B) \dots$  product rule

$P(X|Y) = P(Y|X)P(X)/P(Y)$  Bayes rule

$P(X) = \sum_y P(X, Y=y)$  marginalization

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- Conditioning on background evidence  $E$ :

$$P(A, B, C, \dots | E) = P(A|E) P(B|A, E) P(C|A, B, E) \dots$$

$$P(X|Y, E) = P(Y|X, E)P(X|E)/P(Y|E)$$

$$P(X|E) = \sum_y P(X, Y=y|E)$$

# Marginal and conditional independence

- Marginal independence

$$P(X|Y) = P(X)$$

$$P(Y|X) = P(Y)$$

$$P(X, Y) = P(X)P(Y)$$

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implies the  
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- Conditional independence

$$P(X|Y, E) = P(X|E)$$

$$P(Y|X, E) = P(Y|E)$$

$$P(X, Y|E) = P(X|E)P(Y|E)$$

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# Example of conditional dependence



- $B$  and  $E$  are marginally independent:

$$P(B) = P(B|E)$$

$$P(E) = P(E|B)$$

$$P(B, E) = P(B)P(E)$$

# Example of conditional dependence



- $B$  and  $E$  are marginally independent:

$$P(B) = P(B|E)$$

$$P(E) = P(E|B)$$

$$P(B, E) = P(B)P(E)$$

- But  $B$  and  $E$  are conditionally dependent given  $A$ :

$$P(B|A) \neq P(B|E, A)$$

$$P(E|A) \neq P(E|B, A)$$

$$P(B, E|A) \neq P(B|A)P(E|A)$$

# Joint Distributions and Inference

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- A. Only marginals,  $P(X_j)$
- B. Only conditionals,  $P(X_j|X_j)$
- C. Any marginal or conditional over the variables
- D. None of the above

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**Inference:** Compute the **posterior** distribution of query variables given observed evidence.

- Model complexity

Suppose  $X_i \in \{0, 1\}$  are binary random variables.

# Motivation

- Model complexity

Suppose  $X_i \in \{0, 1\}$  are binary random variables.

How many numbers do we need to specify the joint distribution of  $P(X_1=x_1, \dots, X_n=x_n)$ ?

A.  $O(n)$

B.  $O(2^n)$

C.  $O(n^2)$

D.  $O(\log n)$

$$P(x_1=1, x_2=1)$$

$$P(x_1=0, x_2=1)$$

$$P(x_1=1, x_2=0)$$

$$=0 \quad =0$$

# Motivation

- Model complexity

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It requires  $O(2^n)$  numbers to specify the joint distribution  $P(X_1 = x_1, \dots, X_n = x_n)$ .

Representation

- **Representation:** compactly encode the joint.

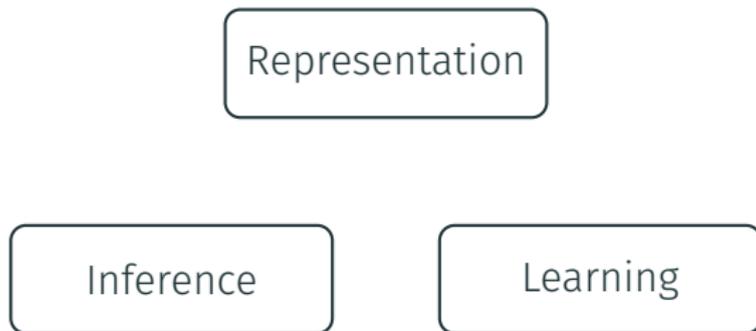
# Conceptual and Practical Goals

Representation

Inference

- **Representation:** compactly encode the joint.
- **Inference:** answer queries given evidence.

# Conceptual and Practical Goals

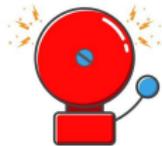


- **Representation:** compactly encode the joint.
- **Inference:** answer queries given evidence.
- **Learning:** estimate structure/parameters from data.

## Alarm Example

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# Alarm example



# Alarm example



- Binary random variables

$B \in \{0, 1\}$  Was there a burglary?

$E \in \{0, 1\}$  Was there an earthquake?

$A \in \{0, 1\}$  Was the alarm triggered?

$J \in \{0, 1\}$  Did Jamal call?

$M \in \{0, 1\}$  Did Maya call?

- Product rule

$$P(B, E, A, J, M)$$

- Product rule

$$P(B, E, A, J, M)$$

$$= P(B)$$

- Product rule

$$\begin{aligned} P(B, E, A, J, M) \\ = P(B) P(E|B) \end{aligned}$$

- Product rule

$$P(B, E, A, J, M)$$

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$$= P(B) P(E|B) P(A|B, E) P(J|B, E, A) P(M|B, E, A, J)$$

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*Note: the above is true no matter what the variables signify.*

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- Domain-specific assumptions

# Joint distribution

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$$P(B, E, A, J, M) \quad \downarrow$$
$$= P(B) P(E|B) P(A|B, E) P(J|B, E, A) P(M|B, E, A, J)$$

*Note: the above is true no matter what the variables signify.*

- Domain-specific assumptions

$$\underline{P(E|B)} = \underline{P(E)} \quad \text{marginal independence}$$

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*Note: the above is true no matter what the variables signify.*

- Domain-specific assumptions

$$P(E|B) = P(E) \quad \text{marginal independence}$$
$$\rightarrow P(J|B, E, A) = P(J|A) \quad \text{conditional independence}$$

- Product rule

$$P(B, E, A, J, M)$$



$$= P(B) P(E|B) P(A|B, E) P(J|B, E, A) P(M|B, E, A, J)$$

*Note: the above is true no matter what the variables signify.*

- Domain-specific assumptions

$$P(E|B) = P(E) \quad \text{marginal independence}$$

$$P(J|B, E, A) = P(J|A) \quad \text{conditional independence}$$

$$P(M|B, E, A, J) = P(M|A) \quad \text{conditional independence}$$

# Completing the model

- Joint distribution

$$P(B, E, A, J, M)$$

$$= P(B) P(E|B) P(A|B, E) P(J|B, E, A) P(M|B, E, A, J)$$

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- Conditional probability tables (CPTs)

$$P(B=1) = 0.001$$

$$P(E=1) = 0.002$$

# Completing the model

- Joint distribution

$$\begin{aligned} P(B, E, A, J, M) \\ &= P(B) P(E|B) P(A|B, E) P(J|B, E, A) P(M|B, E, A, J) \\ &= P(B) P(E) P(A|B, E) P(J|A) P(M|A) \end{aligned}$$

- Conditional probability tables (CPTs)

$$P(B=1) = 0.001$$

$$P(E=1) = 0.002$$

B	E	$P(A=1 B, E)$
0	0	0.001
1	0	0.94
0	1	0.29
1	1	0.95

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J | B | A  
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0	0	0.001
1	0	0.94
0	1	0.29
1	1	0.95

A	$P(J=1 A)$
0	0.05
1	0.9

A	$P(M=1 A)$
0	0.01
1	0.7

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**But this approach can be very inefficient!**

How to perform inference most efficiently?

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1. Visualize models as directed acyclic graphs.
2. Exploit graph structure to organize and simplify calculations.

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2. Exploit graph structure to organize and simplify calculations.

*We'll spend today on (1) and next lecture on (2).*

# Visualizing the model

- Joint distribution

$$P(B, E, A, J, M)$$

$$= P(B) P(E|B) P(A|B, E) P(J|B, E, A) P(M|B, E, A, J)$$

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# Visualizing the model

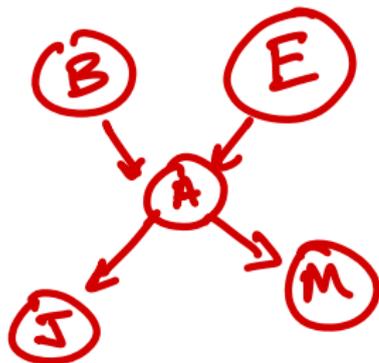
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- Directed acyclic graph (DAG)



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Absent edges encode assumptions of independence.

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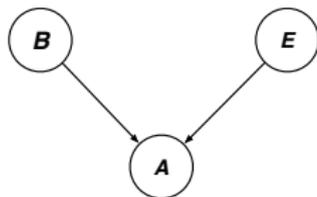
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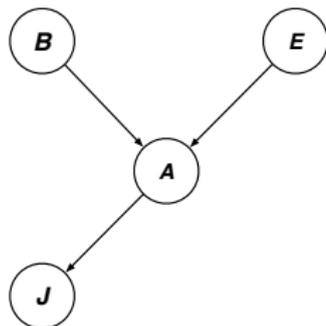
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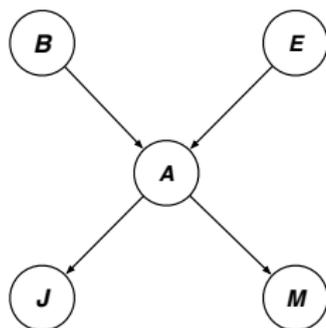
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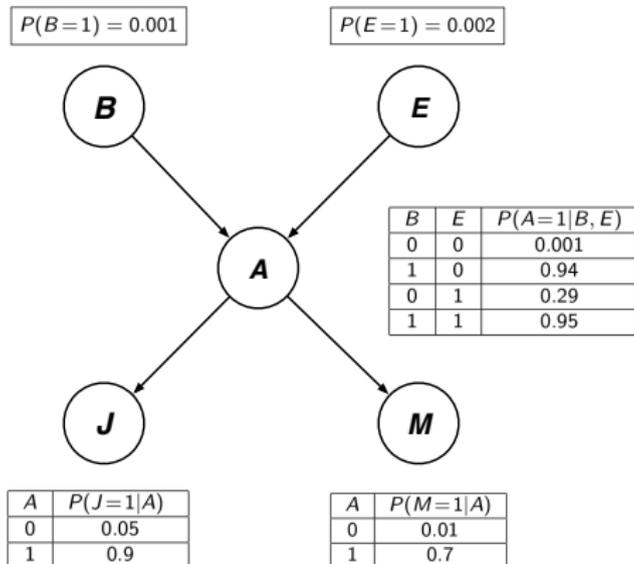
$$= P(B) P(E) P(A|B, E) P(J|A) P(M|A)$$

- Directed acyclic graph (DAG)



Absent edges encode assumptions of independence.

# Alarm belief network



This visual representation of the joint distribution is called a **belief network** (or a **Bayesian network**, or a **probabilistic graphical model**).

# Belief networks

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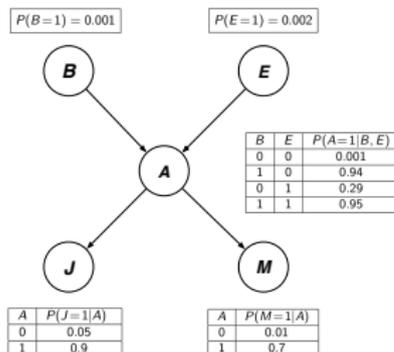
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# Definition

A **belief network** (BN) is a directed acyclic graph (DAG) in which:

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BN = DAG + CPTs



# From distributions to graphs

- It is always true from the product rule that

$$P(X_1, X_2, \dots, X_n) = P(X_1) P(X_2|X_1) \dots P(X_n|X_1, \dots, X_{n-1})$$

- It is always true from the product rule that

$$\begin{aligned} P(X_1, X_2, \dots, X_n) &= P(X_1) P(X_2|X_1) \dots P(X_n|X_1, \dots, X_{n-1}) \\ &= \prod_{i=1}^n P(X_i|X_1, X_2, \dots, X_{i-1}) \end{aligned}$$

## From distributions to graphs

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- But suppose in a particular domain that

$$P(X_i|X_1, X_2, \dots, X_{i-1}) = P(X_i|\text{parents}(X_i)),$$

where  $\text{parents}(X_i)$  is a subset of  $\{X_1, \dots, X_{i-1}\}$ .

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- **Big idea:** represent conditional dependencies by a DAG.

# Constructing a belief network

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1. Choose your random variables of interest.

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  - (a) add the node  $X_i$  to the network

# Constructing a belief network

## Three steps:

1. Choose your random variables of interest.
2. Choose an ordering of these variables (e.g.,  $X_1, X_2, \dots, X_n$ ).
3. While there are variables left:
  - (a) add the node  $X_i$  to the network
  - (b) set the parents of  $X_i$  to be the minimal subset satisfying

$$P(X_1, X_2, \dots, X_n) = \prod_{i=1}^n P(X_i | \text{parents}(X_i)),$$

# Constructing a belief network

## Three steps:

1. Choose your random variables of interest.
2. Choose an ordering of these variables (e.g.,  $X_1, X_2, \dots, X_n$ ).
3. While there are variables left:
  - (a) add the node  $X_i$  to the network
  - (b) set the parents of  $X_i$  to be the minimal subset satisfying

$$P(X_1, X_2, \dots, X_n) = \prod_{i=1}^n P(X_i | \text{parents}(X_i)),$$

- (c) define the conditional probability table  $P(X_i | \text{parents}(X_i))$



- **Best ordering:**

Add the “root causes,” then the variables they influence, then the next variables that are influenced, etc.

# Node ordering

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- **Example:**

In the alarm world, a natural ordering is  $(B, E, A, J, M)$ .

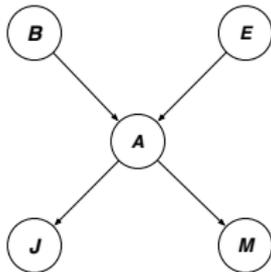
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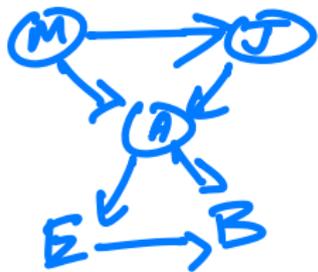
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- What happens if we choose an unnatural ordering?

Ex: (M, J, A, E, B)

- Adding nodes with this ordering:



$P(M, J, A, E, B)$

$$= P(M) P(\underline{J|M}) P(\underline{E|A})$$

$$\rightarrow P(A|JM) P(E|AJM)$$

$$P(B|EAJM)$$

$$\# P(B|A, E)$$

$$\# P(B|A)$$

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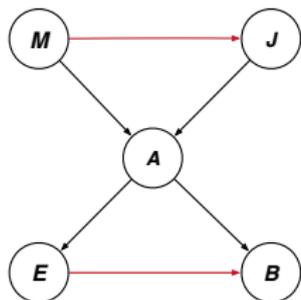
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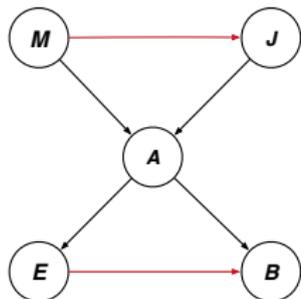
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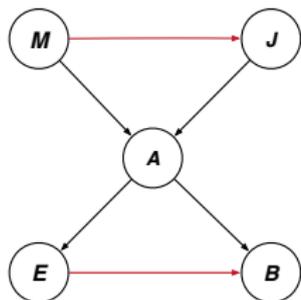
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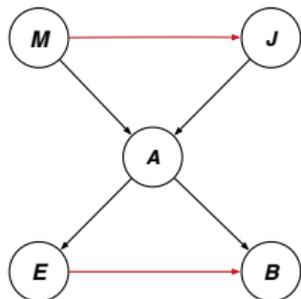
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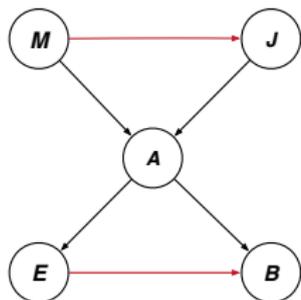
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These CPTs may be more difficult to assess.

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### **Qualitative**

DAGs encode assumptions of marginal and conditional independence.

### **Quantitative**

CPTs encode numerical influences of some variables on others.

That's all folks!